

Linear stability of Euler equations in cylindrical domain

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Flow equations

- inviscid incompressible flow
- cylindrical coordinate system (r, φ, z) rotating about z -axis with angular velocity Ω
- Euler equations

$$\begin{aligned} \frac{dw_r}{dt} - \frac{w_\varphi^2}{r} - 2\Omega w_\varphi - \Omega^2 r + \frac{1}{\rho} \frac{\partial p}{\partial r} &= 0 \\ \frac{dw_\varphi}{dt} + \frac{w_r w_\varphi}{r} + 2\Omega w_r + \frac{1}{\rho r} \frac{\partial p}{\partial \varphi} &= 0 \\ \frac{dw_z}{dt} + \frac{1}{\rho} \frac{\partial p}{\partial z} &= 0 \end{aligned} \quad (1.1)$$

- w_r, w_φ, w_z radial, circumferential and axial velocity
- p pressure
- ρ density

- material derivative

$$\frac{d}{dt} = \frac{\partial}{\partial t} + w_r \frac{\partial}{\partial r} + \frac{w_\varphi}{r} \frac{\partial}{\partial \varphi} + w_z \frac{\partial}{\partial z}$$

- continuity equation

$$\frac{1}{r} \frac{\partial}{\partial r} (r w_r) + \frac{1}{r} \frac{\partial w_\varphi}{\partial \varphi} + \frac{\partial w_z}{\partial z} = 0 \quad (1.2)$$

- solution domain

$$Q = \{(r, \varphi, z) \mid R_1 < r < R_2, 0 \leq \varphi < 2\pi, 0 < z < L\}$$

- base flow with axial symmetry

$$w_{0r}(r, z), \quad w_{0\varphi}(r, z), \quad w_{0z}(r, z), \quad p_0(r, z)$$

- boundary conditions

- inflow region S_1 , $z = 0$: $w_{0r}, w_{0\varphi}, w_{0z}$
- outflow region S_2 , $z = L$: p_0
- free surface Γ_1 , $r = R_1$: p_0 or *surface tension conditions*
- fixed wall Γ_2 , $r = R_2$: w_{0r}

Linear stability

- perturbed state

$$(w_r, w_\varphi, w_z, p) = (w_{0r}, w_{0\varphi}, w_{0z}, p_0) + \varepsilon(v_r, v_\varphi, v_z, \sigma) \quad (2.1)$$

- small parameter ε
- disturbances

$$v_r = v_r(r, \varphi, z, t), \quad v_\varphi = v_\varphi(r, \varphi, z, t)$$

$$v_z = v_z(r, \varphi, z, t), \quad \sigma = \sigma(r, \varphi, z, t)$$

- stability

$$(w_r, w_\varphi, w_z, p) \rightarrow (w_{0r}, w_{0\varphi}, w_{0z}, p_0) \quad \text{for } t \rightarrow \infty$$

- linear stability: insert (2.1) into (1.1), (1.2)

neglect terms with ε^2

- linearized Euler equations

$$\frac{\partial v_r}{\partial t} + w_{0r} \frac{\partial v_r}{\partial r} + \frac{w_{0\varphi}}{r} \frac{\partial v_r}{\partial \varphi} + w_{0z} \frac{\partial v_r}{\partial z} + \frac{\partial w_{0r}}{\partial r} v_r + \frac{\partial w_{0r}}{\partial z} v_z -$$

$$- \frac{2}{r} w_{0\varphi} v_\varphi - 2\Omega v_\varphi + \frac{1}{\rho} \frac{\partial \sigma}{\partial r} = 0,$$

$$\frac{\partial v_\varphi}{\partial t} + w_{0r} \frac{\partial v_\varphi}{\partial r} + \frac{w_{0\varphi}}{r} \frac{\partial v_\varphi}{\partial \varphi} + w_{0z} \frac{\partial v_\varphi}{\partial z} + \frac{\partial w_{0\varphi}}{\partial r} v_r + \frac{\partial w_{0\varphi}}{\partial z} v_z +$$

$$+ \frac{w_{0r}}{r} v_\varphi + \frac{w_{0\varphi}}{r} v_r + 2\Omega v_r + \frac{1}{\rho r} \frac{\partial \sigma}{\partial \varphi} = 0,$$

$$\frac{\partial v_z}{\partial t} + w_{0r} \frac{\partial v_z}{\partial r} + \frac{w_{0\varphi}}{r} \frac{\partial v_z}{\partial \varphi} + w_{0z} \frac{\partial v_z}{\partial z} + \frac{\partial w_{0z}}{\partial r} v_r + \frac{\partial w_{0z}}{\partial z} v_z + \frac{1}{\rho} \frac{\partial \sigma}{\partial z} = 0$$

- continuity equation

$$\frac{1}{r} \frac{\partial}{\partial r} (r v_r) + \frac{1}{r} \frac{\partial v_\varphi}{\partial \varphi} + \frac{\partial v_z}{\partial z} = 0$$

- boundary conditions on S_1, S_2, Γ_2

$$\begin{array}{rcl}
 v_r = v_\varphi = v_z = 0 & & S_1 \\
 \sigma = 0 & \text{on} & S_2 \\
 v_r = 0 & & \Gamma_2
 \end{array}$$

- boundary condition on Γ_1
 - a) in case without surface tension

$$\sigma = 0 \quad \text{on} \quad \Gamma_1$$

b) in case with surface tension

$\Delta(\varphi, z, t)$... radial displacement of Γ_1

σ_p ... surface tension coefficient

- impermeability equation

$$v_r = \frac{\partial \Delta}{\partial t} + w_{0z} \frac{\partial \Delta}{\partial z} \quad \text{on } \Gamma_1$$

- Young-Laplace equation

$$\sigma = \sigma_p \left(\frac{\partial^2 \Delta}{\partial z^2} + \frac{1}{R_1^2} \frac{\partial^2 \Delta}{\partial \varphi^2} \right) \quad \text{on } \Gamma_1$$

- initial condition

$$\Delta = 0 \quad \text{on } \bar{\Gamma}_1 \cap \bar{S}_1$$

- stability $\iff (v_r, v_\varphi, v_z, \sigma, \Delta) \rightarrow (0, 0, 0, 0, 0)$ for $t \rightarrow \infty$

Eigenvalue problem

- modal analysis: separation of variables t, φ taking normal modes

$$v_r(r, \varphi, z, t) = e^{\lambda t + In\varphi} u_r(r, z)$$

$$v_\varphi(r, \varphi, z, t) = e^{\lambda t + In\varphi} u_\varphi(r, z)$$

$$v_z(r, \varphi, z, t) = e^{\lambda t + In\varphi} u_z(r, z)$$

$$\sigma(r, \varphi, z, t) = e^{\lambda t + In\varphi} h(r, z)$$

$$\Delta(\varphi, z, t) = e^{\lambda t + In\varphi} \delta(z)$$

$I = \sqrt{-1}$... imaginary unit

$\lambda \in \mathbb{C}$... eigenvalue

$n \in \mathbb{N}_0 = \{0, 1, 2, \dots\}$... azimuthal wave number

$u_r, u_\varphi, u_z, h : D \mapsto \mathbb{C}, \delta : \langle 0, L \rangle \mapsto \mathbb{C}$ eigenfunctions (normal modes)

$$D = \{(r, z) \mid R_1 \leq r \leq R_2, 0 \leq z \leq L\}$$

- eigenvalue problem

$$\lambda u_r + w_{0r} \frac{\partial u_r}{\partial r} + w_{0\varphi} \frac{nI}{r} u_r + w_{0z} \frac{\partial u_r}{\partial z} + \frac{\partial w_{0r}}{\partial r} u_r + \frac{\partial w_{0r}}{\partial z} u_z -$$

$$- \frac{2}{r} w_{0\varphi} u_\varphi - 2\Omega u_\varphi + \frac{1}{\rho} \frac{\partial h}{\partial r} = 0$$

$$\lambda u_\varphi + w_{0r} \frac{\partial u_\varphi}{\partial r} + \frac{nI}{r} w_{0\varphi} u_\varphi + w_{0z} \frac{\partial u_\varphi}{\partial z} + \frac{\partial w_{0\varphi}}{\partial r} u_r + \frac{\partial w_{0\varphi}}{\partial z} u_z +$$

$$+ \frac{w_{0r}}{r} u_\varphi + \frac{w_{0\varphi}}{r} u_r + 2\Omega u_r + \frac{nI}{\rho r} h = 0$$

$$\lambda u_z + w_{0r} \frac{\partial u_z}{\partial r} + \frac{nI}{r} w_{0\varphi} u_z + w_{0z} \frac{\partial u_z}{\partial z} + \frac{\partial w_{0z}}{\partial r} u_r + \frac{\partial w_{0z}}{\partial z} u_z + \frac{1}{\rho} \frac{\partial h}{\partial z} = 0$$

$$\frac{1}{r} \frac{\partial}{\partial r} (r u_r) + \frac{nI}{r} u_\varphi + \frac{\partial u_z}{\partial z} = 0$$

- in case with surface tension

$$\lambda \delta + w_{0z}(R_1, z) \delta' - u_r(R_1, z) = 0$$

- boundary conditions

$$S_1 \cap D : \quad u_r = u_\varphi = u_z = 0$$

$$S_2 \cap D : \quad h = 0$$

$$\Gamma_1 \cap D : \quad \begin{cases} h = 0 & \text{(without surface tension)} \\ h = \sigma_p \left(\delta'' - \frac{n^2}{R_1^2} \delta \right), \quad \delta(0) = 0 & \text{(with surface tension)} \end{cases}$$

$$\Gamma_2 \cap D : \quad u_r = 0$$

- stability $\iff \operatorname{Re}(\lambda) < 0$
- $n = 0 \implies$ rotationally symmetric flow

Discretization

- approximate finite-dimensional eigenvalue problem obtained by spectral element method (SEM) \equiv hp-finite element method (hp-FEM)
- algorithm implemented in MATLAB \implies eustab
- generalized eigenvalue problem

$$\mathbf{A}\mathbf{u} = \lambda\mathbf{B}\mathbf{u} \quad (4.1)$$

solved by means of MATLAB functions `eig` and `eigs`

- domain partition: set $\{D^{ij}\}$ of concurrent rectangles

$$D = \bigcup D^{ij}, \quad i = 1, \dots, n_r, \quad j = 1, \dots, n_z$$

- spectral element
 - domain D^{ij}
 - shape function: polynomial of degree N in both r, z
 - degrees of freedom: values at nodes of product Gauss-Legendre-Lobatto (GLL) quadrature formula of order $2N - 1$
- solution method: Galerkin with GLL numerical integration
- test functions
 - r -momentum eq. : $w_r, = 0$ for $z = 0$ or $r = R_2$
 - φ -momentum eq. : $w_\varphi, = 0$ for $z = 0$
 - z -momentum eq. : $w_z, = 0$ for $z = 0$
 - continuity eq. : $w_p, = 0$ for $z = L$ or $r = R_1$
 - impermeability eq. : $w_\delta, = 0$ for $z = 0$
 - Young-Laplace eq. : $w_\sigma, = 0$ for $z = L$

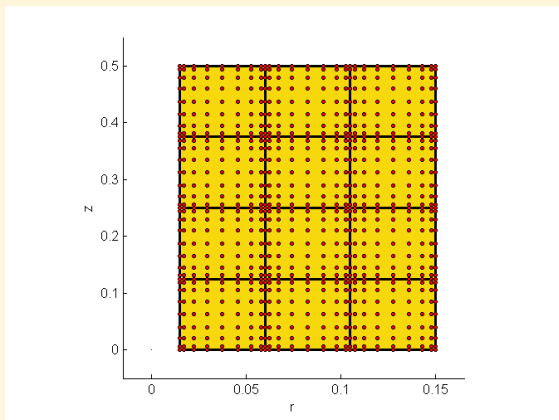


Figure: Net, $n_r = 3$, $n_z = 4$, $N = 8$, 825 nodes.

- solution of the eigenvalue problem

$$\mathbf{A}\mathbf{u} = \lambda\mathbf{B}\mathbf{u}$$

in MATLAB

- \mathbf{A} is regular, nonhermitian, real for $n = 0$ and complex for $n > 0$
- \mathbf{B} is diagonal and singular: diagonal elements corresponding to continuity equation and Young-Laplace equation are equal to zero, remaining diagonal coefficients are real and positive
- there are $n_\infty = 2n_h + n_\delta$ infinite eigenvalues, where n_h and n_δ is number of degrees of freedom of pressure h and free boundary displacement δ , respectively

- m-function eig:
 - based on LAPACK
 - arbitrary \mathbf{A} , \mathbf{B}
 - all eigenvalues and eigenvectors
 - robust, expensive
- m-function eigs:
 - based on ARPACK
 - \mathbf{A} arbitrary, \mathbf{B} hermitian (however, it works in our case)
 - a few eigenvalues and eigenvectors
 - lower computer time and computer memory demands
 - problem: how to specify a set of eigenvalues which we want to find?
 - maximum real part ... impossible due to infinite eigenvalues
 - closest to a specified complex number... but how to choose it?

Following numerical experiments: with m-function eig

Results of numerical experiments

- Example 1.
- constant stationary velocities

$w_{0r} = w_{0\varphi} = 0, w_{0z} = C_0$, where

$$R_0 = 0.015 \quad [\text{m}] \quad \Omega = 5 \quad [\text{rad} \cdot \text{s}^{-1}]$$

$$R_2 = 0.15 \quad [\text{m}] \quad \rho = 1000 \quad [\text{kg} \cdot \text{m}^{-3}]$$

$$L = 0.5 \quad [\text{m}] \quad \sigma_p = 0.073 \quad [\text{N} \cdot \text{m}]$$

$$C_0 = 1 \quad [\text{m} \cdot \text{s}^{-1}] \quad n = 0, 1, 2 \quad [\text{whole numbers}]$$

- discretization: $n_r = n_z = 1, N = 8$
- surface tension influence is insignificant \implies presented results computed without surface tension

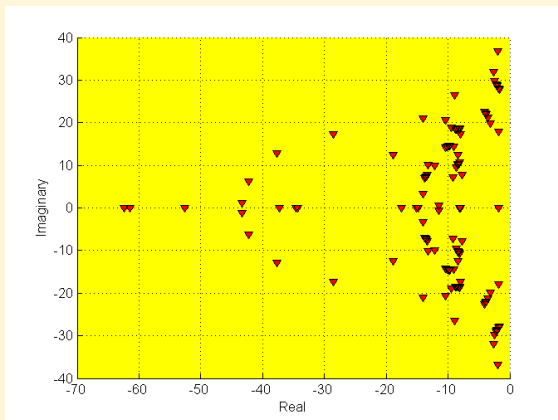


Figure: Ex1-0, eigenvalues, $n = 0$.

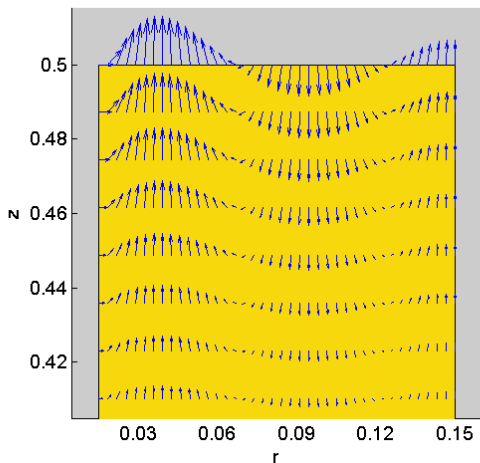


Figure: Ex1-1, real part of the eigenfunction for $n = 0$, $\lambda = -14.91$, meridial section for $\varphi = 0$.

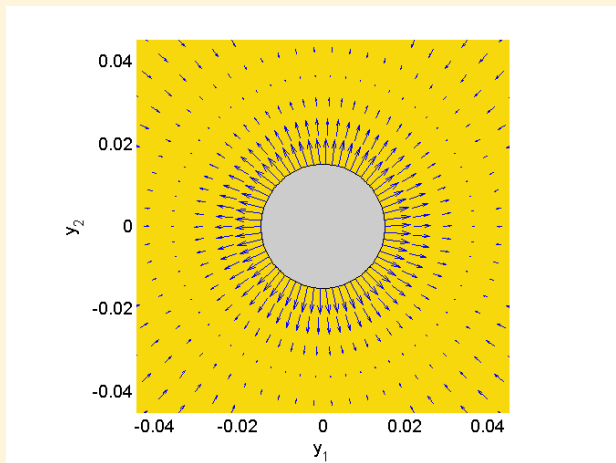


Figure: Ex1-2, real part of the eigenfunction for $n = 0$, $\lambda = -14.91$, normal section for $z = 0.5$.

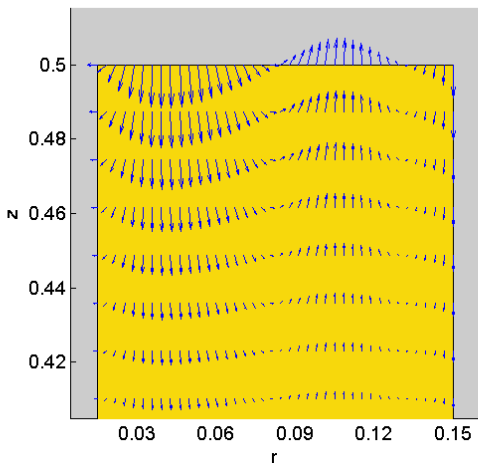


Figure: Ex1-3, real part of the eigenfunction for $n = 1$, $\lambda = -14.91$, meridial section for $\varphi = 0$.

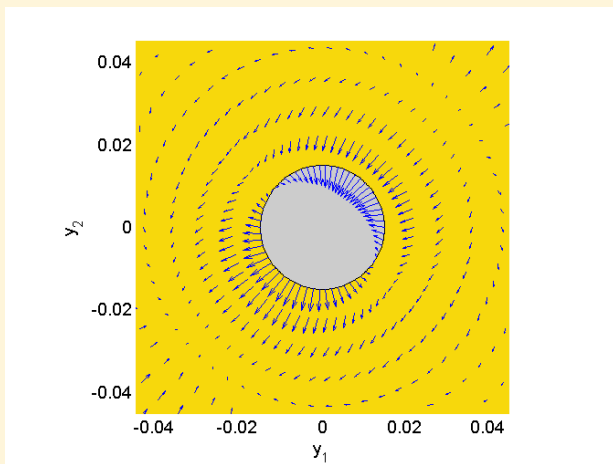


Figure: Ex1-4, real part of the eigenfunction for $n = 1$, $\lambda = -14.91$, normal section for $z = 0.5$.

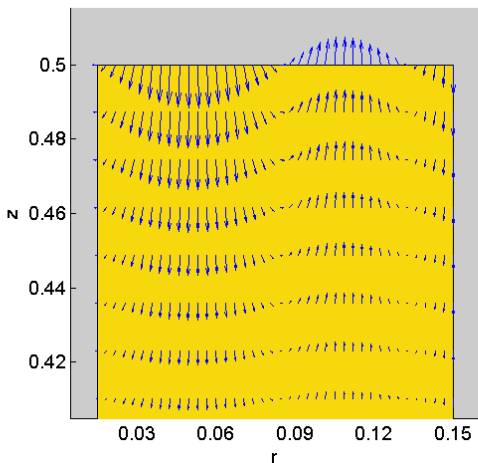


Figure: Ex1-5, real part of the eigenfunction for $n = 2$, $\lambda = -14.88$, meridial section for $\varphi = 0$.

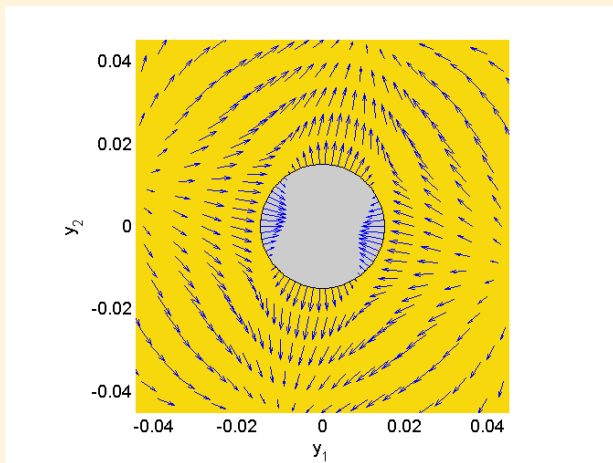


Figure: Ex1-6, real part of the eigenfunction for $n = 2$, $\lambda = -14.88$, normal section for $z = 0.5$.

- 3136 eigenvalues, 1600 finite eigenvalues, $\max \operatorname{Re}(\lambda) \approx -0.04$

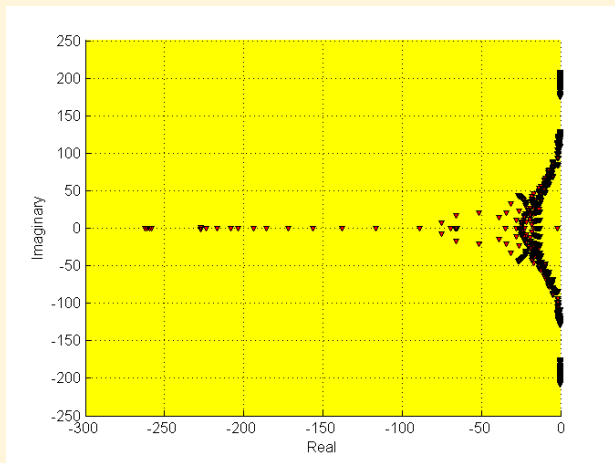


Figure: Ex1-7, eigenvalues, $n_r = 3$, $n_z = 4$, $N = 8$.

- Example 2.
- constant velocities $w_{0r} = 0$, $w_{0z} = C_0$, circumferential velocity

$$c_{0\varphi} = w_{0\varphi}(r) + \Omega r$$

- data as in example 1
- four circumferential velocities in figures Ex2-1, Ex2-2, Ex2-3, Ex2-4
- corresponding maximal real parts of eigenvalues in table Ex2
- computations accomplished for $n_r = 2$, $n_z = 1$, $N = 8$, $n = 0$, without surface tension

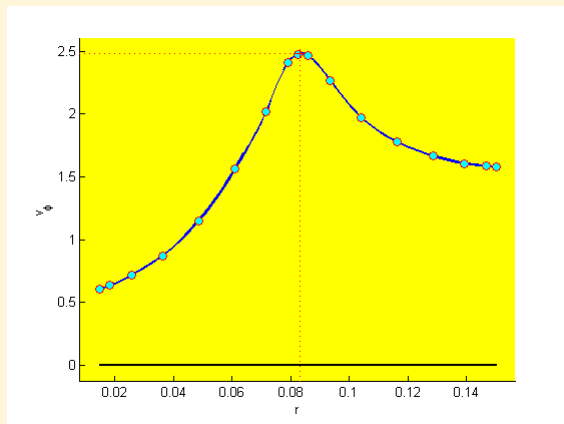


Figure: Ex2-1, $\max c_{0\varphi} = c_{0\varphi}(0.083) = 2.48$

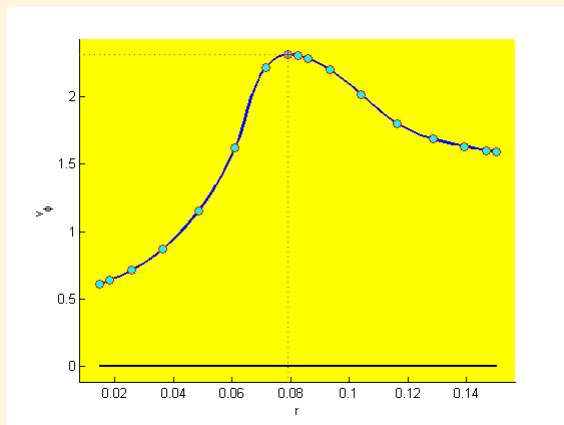


Figure: Ex2-2, $\max c_{0\varphi} = c_{0\varphi}(0.079) = 2.31$

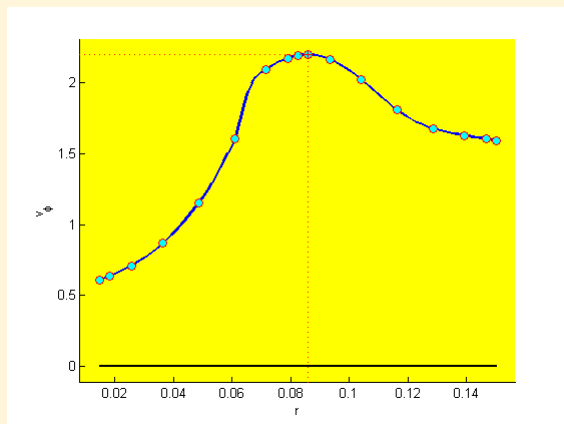


Figure: Ex2-3, $\max c_{0\varphi} = c_{0\varphi}(0.086) = 2.20$

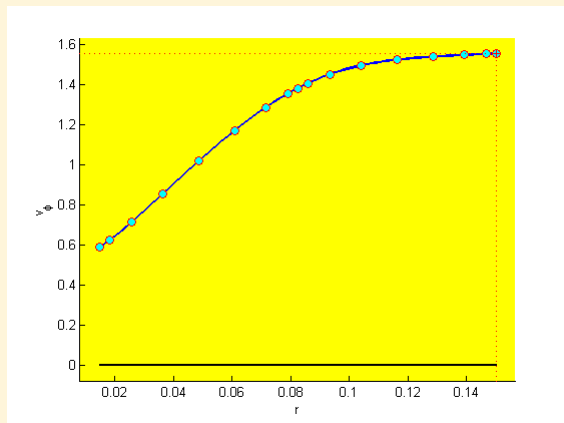


Figure: Ex2-4, $\max c_{0\varphi} = c_{0\varphi}(0.150) = 1.56$

- stability results for circumferential velocities $c_{0\varphi}$ corresponding previous figures

r_{max}	0.083	0.079	0.086	0.150
$c_{0\varphi,max}$	2.48	2.31	2.20	1.56
$\max \operatorname{Re}(\lambda), n = 0$	0.73	-0.03	-0.03	-0.79
$\max \operatorname{Re}(\lambda), n = 1$	2.44	0.16	-0.25	-0.51
$\max \operatorname{Re}(\lambda), n = 2$	2.08	0.57	0.25	-1.62

Table: Ex2, stability for $c_{0\varphi}$ in accordance with figures Ex2-1, Ex2-2, Ex2-3, Ex2-4

- Example 3.
- constant velocities $w_{0r} = 0$, $w_{0z} = C_0$, inflow circumferential velocity

$$w_{0\varphi} = \Omega r (ae^{-r/b} - 1), \quad a = 1.5, b = 0.05,$$

$$c_{0\varphi} = w_{0\varphi} + \Omega r, \text{ see figure Ex3-1}$$

- other data

$$R_0 = 0.015 \quad [\text{m}]$$

$$C_0 = 1 \quad [\text{m} \cdot \text{s}^{-1}]$$

$$R_2 = 0.15 \quad [\text{m}]$$

$$\Omega = 5 \quad [\text{rad} \cdot \text{s}^{-1}]$$

$$L = 1 \quad [\text{m}]$$

$$\rho = 1000 \quad [\text{kg} \cdot \text{m}^{-3}]$$

- computations accomplished for $n_r = 4$, $n_z = 1$, $N = 8$, $n = 0$, without surface tension

- inflow circumferential velocity $c_{0\varphi} = 7.5re^{-r/0.05}$

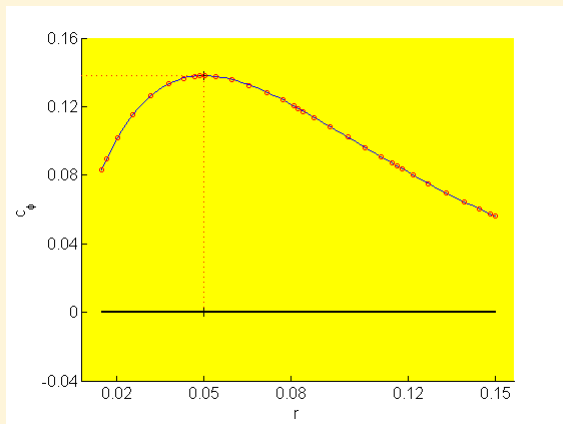


Figure: Ex3-1, $\max c_{0\varphi} = c_{0\varphi}(0.05) = 0.138$

- eigenvalues for $w_{0r} = 0$, $w_{0\varphi} = 5r(1.5e^{-r/0.05} - 1)$, $w_{0z} = 1$

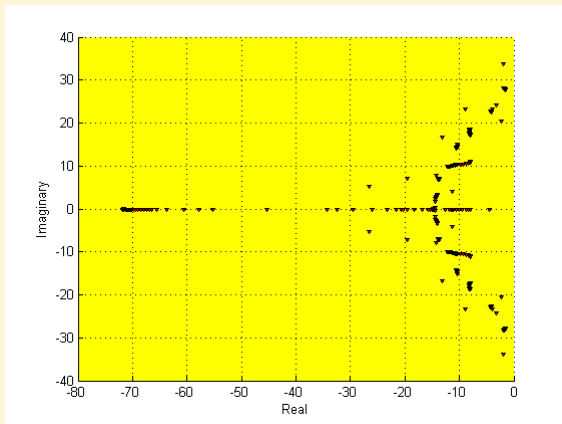


Figure: Ex3-2, $\max \operatorname{Re}(\lambda) = -1.61$

- eigenvalues for flow field computed by FLUENT for boundary conditions

$$z = 0 : \quad w_r = 0, w_{0\varphi} = 5r(1.5e^{-r/0.05} - 1), w_z = 1$$

$$z = L : \quad p = p_{cvr} \quad (\text{constant pressure invoking cavitating vortex rope})$$

$$r = R_1 : \quad p = p_{sv} \quad (\text{constant saturated vapour pressure})$$

$$r = R_2 : \quad w_r = 0$$

see figure Ex3-3

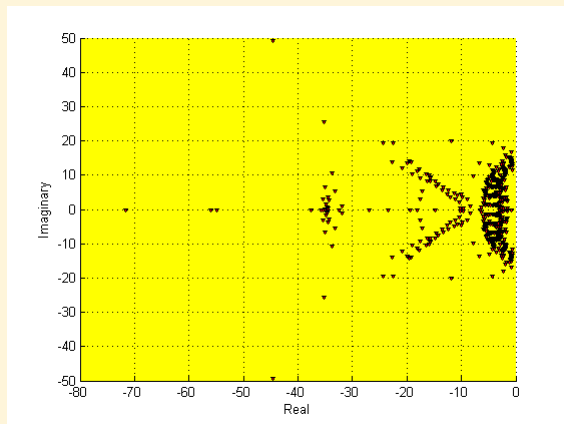


Figure: Ex3-3, $\max \operatorname{Re}(\lambda) = -0.67$

Literature

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